

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (Currently Amended) A gripper assembly for picking and placing vessels, comprising:

- a. a cylinder having an end rim;
- b. at least two gripping member members, extending from said end rim of said cylinder in a spaced-apart relationship for receiving therebetween a vessel, wherein said gripping members have a spring-line property that allows their deflection when said vessel is inserted therebetween and holding it said vessel by friction;
- c. a piston slidably inserted inside said cylinder; and
- d. a plunger connected to and movable with said piston, and extending between said gripping members for engaging said vessel.

2. (Original) The gripper assembly of claim 1, further comprising an adapter for mounting said gripper assembly to a positioning mechanism.

3. (Original) The gripper assembly of claim 1, wherein at least one of said gripping members is made of semi-rigid flexible material.

4. (Original) The gripper assembly of claim 3, wherein said material is plastic material.

5. (Original) The gripper assembly of claim 1, wherein said gripping members each have a chamfered bottom end for receiving a misaligned vessel.

6. (Original) The gripper assembly of claim 1, further comprising pneumatic means for actuating said piston to push said plunger for releasing said vessel from said gripping members.

7. (Original) The gripper assembly of claim 6, wherein said pneumatic means actuates said piston by supplying pressurized air into said cylinder.

8. (Original) The gripper assembly of claim 1, further comprising means for detecting whether said vessel has been picked up.

9. (Original) The gripper assembly of claim 8, wherein said detecting means comprises a magnet mounted to and movable with said piston, and a sensor fixedly mounted on said cylinder for sensing magnetic field of the magnet.

10. (Original) The gripper assembly of claim 1, further comprising means for mixing the contents of said vessel while it is held by said gripping members.

11. (Original) The gripper assembly of claim 10, wherein said mixing means comprises a spin mechanism for spinning said gripper assembly.

12. (Withdrawn) A gripper assembly mounted on a positioning mechanism for picking and placing vessels, comprising:

a. an elongated cylinder having a top end and a bottom rim;
a multiplicity of elongated gripping members with free bottom ends, the gripping members connected to said bottom rim of said cylinder in a spaced-apart relationship such that their bottom ends form a slotted expandable circular opening for receiving a vessel;

b. a piston slidably inserted inside said cylinder;
c. an elongated plunger connected to and movable with said piston, and extending inside said gripping members for engagement with said vessel;

d. said gripping members holding said vessel by friction when said vessel is being transferred; and

e. means for actuating said piston to push down said plunger for releasing said vessel from said gripping members.

13. (Withdrawn) The gripper assembly of claim 12, further comprising an adapter for mounting said gripper assembly to said positioning mechanism.

14. (Withdrawn) The gripper assembly of claim 12, wherein at least one of said gripping members is made of semi-rigid flexible material.

15. (Withdrawn) The gripper assembly of claim 14, wherein said material is plastic material.

16. (Withdrawn) The gripper assembly of claim 12, wherein said bottom ends of said gripping members are chamfered for receiving a misaligned vessel.

17. (Withdrawn) The gripper assembly of claim 12, wherein said plunger is capable of being pushed up by said vessel when said vessel is picked up by said gripping members.

18. (Withdrawn) The gripper assembly of claim 12, wherein said gripping members are capable of being slightly deflected when said vessel is inserted therebetween.

19. (Withdrawn) The gripper assembly of claim 12, wherein said actuating means is a pneumatic actuating means.

20. (Withdrawn) The gripper assembly of claim 19, wherein said pneumatic actuating means actuates said piston by supplying pressurized air into said cylinder.

21. (Withdrawn) The gripper assembly of claim 12, further comprising means for detecting whether said vessel has been picked up.

22. (Withdrawn) The gripper assembly of claim 21, wherein said detecting means comprises a magnet mounted to and movable with said piston, and a sensor fixedly mounted on said cylinder for sensing magnetic field of the magnet.

23. (Original) A method of picking and placing vessels, comprising the steps of:

a. positioning a gripper assembly at a vessel, the gripper assembly including at least two gripping members extending from a cylinder in a spaced-apart relationship, a piston slidably inserted inside the cylinder, and a plunger connected to the piston, and extending between the gripping members;

b. picking up said vessel by moving said gripper assembly towards said vessel such that said vessel is inserted between said gripping members and pushing said plunger away, while leaving a small clearance to allow slight further insertion of said vessel;

c. transferring said vessel as it is held by said gripping members by friction;

d. placing said vessel into a seating;

e. seating said vessel by further moving said gripper assembly slightly towards said seating as allowed by said small clearance to ensure that said vessel is correctly seated; and

f. releasing said vessel by moving said gripper assembly away from said seating.

24. (Original) The method of claim 23, further comprising the step of mounting said gripper assembly to a positioning mechanism for controlling the movement of said gripper assembly.

25. (Original) The method of claim 23, further comprising the step of re-positioning said gripper assembly over a new location before placing said vessel into said seating.

26. (Original) The method of claim 23, further comprising the step of positioning said gripper assembly over the same location before placing said vessel into said seating.

27. (Original) The method of claim 23, further comprising the step of moving said seating to a new location before placing said vessel into said seating.

28. (Original) The method of claim 23, further comprising the step of indexing said seating to a new location before placing said vessel into said seating.

29. (Currently Amended) The method of claim ~~23~~ 40, further comprising the step of supplying pressurized air to said cylinder to actuate said piston.

30. (Original) The method of claim 23, wherein said gripping members each has a chamfered bottom end for receiving a misaligned vessel.

31. (Original) The method of claim 23, further comprising the step of spinning said gripper assembly to mix the content of said vessel while said vessel is transferred.

32. (Withdrawn) A method of picking and placing vessels, comprising the steps of:

a. positioning a gripper assembly at a vessel seated in a seating, the gripper assembly including a plurality of gripping members extending from a cylinder in a spaced-apart relationship, a piston slidably inserted inside the cylinder, and a plunger connected to the piston, and extending between the gripping members;

b. picking up said vessel from said seating by moving said gripper assembly towards said vessel such that said vessel is inserted between said gripping members and pushing said plunger away, while leaving a small clearance to allow slight further insertion of said vessel;

c. mixing the content of said vessel as it is held by said gripping members by friction;

d. placing said vessel back into said seating;

e. seating said vessel by further moving said gripper assembly slightly towards said seating as allowed by said small clearance to ensure that said vessel is correctly seated; and

f. releasing said vessel by moving said gripper assembly away from said seating while actuating said piston to push said plunger which in turn pushes said vessel out of said gripping members.

33. (Withdrawn) The method of claim 32, further comprising the step of mounting said gripper assembly to a positioning mechanism for controlling the movement of said gripper assembly.

34. (Withdrawn) The method of claim 32, further comprising the step of re-positioning said gripper assembly over a new location before placing said vessel back into said seating.

35. (Withdrawn) The method of claim 32, further comprising the step of positioning said gripper assembly over the same location before placing said vessel back into said seating.

36. (Withdrawn) The method of claim 32, further comprising the step of moving said seating to a new location before placing said vessel back into said seating.

37. (Withdrawn) The method of claim 32, further comprising the step of indexing said seating to a new location before placing said vessel back into said seating.

38. (Withdrawn) The method of claim 32, further comprising the step of supply pressurized air to said cylinder to actuate said piston.

39. (Withdrawn) The method of claim 32, wherein said gripping members each has a chamfered bottom end for receiving a misaligned vessel.

40. (New) The method of claim 23, wherein the seating step (e) further comprises actuating said piston to seat said plunger against said vessel.

41. (New) The method of claim 23, wherein the releasing step (f) further comprises holding the vessel in its seating position with said plunger while moving said gripper away from the vessel.

42. (New) The method of claim 41, wherein the plunger remains seated against said vessel until said gripping members completely disengage said vessel.

43. (New) The gripper assembly of claim 8, further comprising an adapter for mounting said gripper assembly to a positioning mechanism, wherein said detecting means comprises a magnet mounted to and movable with said piston, and a sensor fixedly mounted on the adapter.

44. (New) The gripper assembly of claim 8, wherein said detecting means is selected from a group consisting of inductive, capacitive and optical sensors.